# Optimal thinking in forest management with environmental concerns 

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## Sinopse

## 1 Open problem

## 2 Methodologies

## Basic forestry problem



Source: Os Espacialistas


Forest area $=21147.8$ ha $\#$ stands $=1363$ \# periods $=7$

Maximize the profit from timber harvested over the planning horizon subject to:

- A regular production of timber in the planning horizon
- A minimum in the average age of the forest at the end of the planning horizon



## Clearcuts



Limiting clearcut size aims at reducing the impact on

- soil
- water quality
- wildlife
- scenic beauty
- ...


## Mature patches



Forest patch $=$ Edge + Core area
Core area - interior area of the patch where ecological functioning is not impacted by the effect of immediately surrounding conditions

Edge - buffer area separating core area from outside influences

## Edge and core-dependent species



Edge-dependent species


Core-dependent species

The core area of a forest patch is determined by the area, shape and immediately surrounding conditions of the patch

## Core area

The core area of a forest patch is determined by the area, shape and immediately surrounding conditions of the patch

## Area

## Similar shapes

Smaller mature patches $\longleftrightarrow$ Less amount of core area

3.14ha

0:3.14

7.7ha 1:7.7

## Shape

## Similar areas

Elongated or complex shapes $\longleftrightarrow$ Less amount of core area


## Basic + clearcut constraints



Source: Os Espacialistas

## Basic + clearcut constraints

Maximize the profit from timber harvested over the planning horizon subject to:

- A regular production of timber in the planning horizon
- A minimum in the average age of the forest at the end of the planning horizon
- For each period, the area of every clearcut does not exceed the maximum allowed size



## Basic + clearcut + habitat constraints



Source: Os Espacialistas

## Basic + clearcut + habitat constraints

Maximize the profit from timber harvested over the planning horizon subject to:

- A regular production of timber in the planning horizon
- A minimum in the average age of the forest at the end of the planning horizon
- For each period, the area of every clearcut does not exceed the maximum allowed size
- Each habitat is a mature patch meeting a minimum core area
- In each period, the total core area inside habitats is greater than or equal to a minimum total core area



## Operations Research challenges in forestry: $\mathbf{3 3}$ open

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Abstract Forestry has contributed many problems to the Operations Rescarch (OR) community. At the same time, OR hais developed many modelx and solution methods foc uen forestry. In this article. wo describe the current status of research on the application of OR methods to forestry and a number of research challenges or open questions that we believe will be of interest to both researchers and practitioners. The areas covened include strategic chical and operational planning, fire management, conservation and the use of OR to address environmental concems. The paper also considers more general methodological areas tha are important to forestry including uncenainty, multiple objectives and hierarchical plamning.

Keywords Forestry - OR challenges - Transporlation - Harvesting Environment - Fores management - Fire management . Operations research . Strategic. Tactical . Operational

## 1 Introduction

The forest industry is very imporiant from both regional and national perspectives in many countrics. It constitutes a large proportion of the net exports in. for example. Canada. Chile.

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Open Problem 13 How can we include complex environmental considerations like fragmentation, corridors, balancing mature patches, etc. into URM and ARM formulations in a computationally feasible way?

It is well recognized now that adjacency constraints capture only a part of necessary environmental considerations. While maximum opening size limits are important, excessive fragmentation of forests is not particularly satisfactory. In order to allow wildlife to move between habitats, corridors of mature trees need to exist to join them. Similarly, issues of forest edge as well as a balance of mature forest are important for certain species. A few examples exist of attempting to address related issues using heuristic approaches. Thus, exact approaches are needed.

## Modelling issues



## Modelling issues

- Clearcut $\longleftrightarrow$ Connected component of the graph where the nodes are the harvested stands



## Modelling issues

- Mature patch $\longleftrightarrow$ Connected component of the graph where the nodes are mature stands



## Modelling issues

- Core area $\longleftrightarrow$ Connected component of the graph where the nodes are mature stands surrounded by a buffer of non-harvested stands


## Connectivity



Source: Os Espacialistas

## Models in MIP (A)

- $x_{i}^{t}= \begin{cases}1 & \text { if stand } i \text { is selected to be harvested in period } t \\ 0 & \text { otherwise }\end{cases}$
- $y^{t}\left\{\begin{array}{l}1 \text { if stand } i \text { is selected to be part of the core area of }\end{array}\right.$ a habitat in period $t$
0 otherwise


## Models in MIP (A)

- $x_{i}^{t}= \begin{cases}1 & \text { if stand } i \text { is selected to be harvested in period } t \\ 0 & \text { otherwise }\end{cases}$
- $y_{i}^{t}= \begin{cases}1 & \text { if stand } i \text { is selected to be part of the core area of } \\ 0 & \text { a habitat in period } t\end{cases}$
- $\sum_{i \in C} x_{i}^{t} \leq|C|-1 ; t \in T ; C \in \mathcal{C} c^{t}$
- $\sum_{i \in \Pi^{t}(M)} y_{i}^{t} \geq y_{j}^{t} ; t \in T ; M \in \mathcal{M} h^{t} ; j \in M$
- $\sum_{\substack{t^{\prime} \leq t: \\ c^{t^{\prime}} \cap\{i\} \neq \emptyset}} x_{i}^{t^{\prime}} \leq 1-y_{j}^{t} ; t \in T ; j \in M^{t} ; i \in \pi(j) \cup\{j\}$
- $\sum_{i \in M^{t}} a_{i} y_{i}^{t} \geq C O T_{\text {min }} ; t \in T$


## Clearcuts

$$
a_{i}=1 \mathrm{ha}, A_{\max }=2 \mathrm{ha}
$$

| 1 | 2 | 3 |
| :--- | :--- | :--- |
| 4 | 5 | 6 |
| 7 | 8 | 9 |

Mature forest
in period 1

## Clearcuts

Connected region, unfeasible as clearcut, minimal

| 1 | 2 | 3 |
| :--- | :--- | :--- |
| 4 | 5 | 6 |
| 7 | 8 | 9 |

## Clearcuts

| 1 | 2 | 3 |
| :--- | :--- | :--- |
| 4 | 5 | 6 |
| 7 | 8 | 9 |

## Clearcuts

| 1 | 2 | 3 |
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## Clearcuts

| 1 | 2 | 3 |
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| 4 | 5 | 6 |
| 7 | 8 | 9 |

## Clearcuts

| 1 | 2 | 3 |
| :--- | :--- | :--- |
| 4 | 5 | 6 |
| 7 | 8 | 9 |

$$
x_{1}^{1}+x_{2}^{1}+x_{3}^{1} \leq 2
$$

## Clearcuts

| 1 | 2 | 3 |
| :--- | :--- | :--- |
| 4 | 5 | 6 |
| 7 | 8 | 9 |

$$
\begin{aligned}
& x_{1}^{1}+x_{2}^{1}+x_{3}^{1} \leq 2 \\
& \sum_{i \in C} x_{i}^{t} \leq|C|-1 ; \quad t \in T ; C \in \mathcal{C} C^{t}
\end{aligned}
$$

## Core area

$$
a_{i}=1 \text { ha }, C_{\min }=3 \text { ha }
$$

| 1 | 2 | 3 |
| :--- | :--- | :--- |
| 4 | 5 | 6 |
| 7 | 8 | 9 |

Mature forest in period 1

## Core area

Connected region, unfeasible core area

| 1 | 2 | 3 |
| :--- | :--- | :--- |
| 4 | 5 | 6 |
| 7 | 8 | 9 |

## Core area

Connected region, unfeasible core area

| 1 | 2 | 3 |
| :--- | :--- | :--- |
| 4 | 5 | 6 |
| 7 | 8 | 9 |

## Core area

Connected region, unfeasible core area

| 1 | 2 | 3 |
| :--- | :--- | :--- |
| 4 | 5 | 6 |
| 7 | 8 | 9 |

## Core area

## Connected region, unfeasible core area

| 1 | 2 | 3 |
| :--- | :--- | :--- |
| 4 | 5 | 6 |
| 7 | 8 | 9 |

$$
y_{4}^{1}+y_{8}^{1} \geq y_{7}^{1}
$$

## Core area

Connected region, unfeasible core area

| 1 | 2 | 3 |
| :--- | :--- | :--- |
| 4 | 5 | 6 |
| 7 | 8 | 9 |

## Core area

| 1 | 2 | 3 |
| :--- | :--- | :--- |
| 4 | 5 | 6 |
| 7 | 8 | 9 |

## Core area

| 1 | 2 | 3 |
| :--- | :--- | :--- |
| 4 | 5 | 6 |
| 7 | 8 | 9 |

## Core area

| 1 | 2 | 3 |
| :--- | :--- | :--- |
| 4 | 5 | 6 |
| 7 | 8 | 9 |

## Core area

| 1 | 2 | 3 |
| :--- | :--- | :--- |
| 4 | 5 | 6 |
| 7 | 8 | 9 |

$$
\begin{aligned}
& y_{4}^{1}+y_{5}^{1}+y_{9}^{1} \geq y_{7}^{1} \\
& y_{4}^{1}+y_{5}^{1}+y_{9}^{1} \geq y_{8}^{1}
\end{aligned}
$$

## Core area

| 1 | 2 | 3 |
| :--- | :--- | :--- |
| 4 | 5 | 6 |
| 7 | 8 | 9 |

$y_{4}^{1}+y_{5}^{1}+y_{9}^{1} \geq y_{7}^{1}$
$y_{4}^{1}+y_{5}^{1}+y_{9}^{1} \geq y_{8}^{1}$
$\sum_{i \in \Pi^{t}(M)} y_{i}^{t} \geq y_{j}^{t} ; t \in T ; M \in \mathcal{M} h^{t} ; j \in M$

## Habitat

## Habitat

| 1 | 2 | 3 |
| :--- | :--- | :--- |
| 4 | 5 | 6 |
| 7 | 8 | 9 |

$$
\sum_{\substack{t^{\prime} \leq t: \\ c^{t^{\prime} \cap\{i\} \neq \emptyset}}} x_{i}^{t^{\prime}} \leq 1-y_{j}^{t} ; t \in T ; j \in M^{t} ; i \in \pi(j) \cup\{j\}
$$

- Polynomial number of variables
- Exponential number of constraints
- Polynomial number of variables
- Exponential number of constraints


## Branch-and-cut $\longrightarrow$

Solutions within $1 \%$ of the optimum in less than three hours

## Models in MIP (B)

- $z_{c}^{t}= \begin{cases}1 & \text { if region } c \in \mathcal{C}^{t} \\ 0 & \text { otherwise harvested in period } t\end{cases}$
- $y_{h}^{t}= \begin{cases}1 & \text { if region } h \in \mathcal{H}^{t} \text { is habitat in period } t \\ 0 & \text { otherwise }\end{cases}$
- $w_{\text {ir }}^{t}= \begin{cases}1 & \text { if subregion } r \in \mathcal{R}_{i} \text { is core habitat in period } t \\ 0 & \text { otherwise }\end{cases}$


## Clearcuts

## Region $c \in \mathcal{C}^{1}$ that can be a clearcut in period 1 if ...

| 1 | 2 | 3 |
| :--- | :--- | :--- |
| 4 | 5 | 6 |
| 7 | 8 | 9 |

## Habitats

Region $h \in \mathcal{H}^{1}$ that can be a habitat in period 1 if ...

| 1 | 2 | 3 |
| :--- | :--- | :--- |
| 4 | 5 | 6 |
| 7 | 8 | 9 |

## Core area - Subregions



## Core area



## Core area



## Core area



## Core area



## Constraints

- $\sum_{u=1}^{t} \sum_{c \in \mathcal{C}^{u}: i \in c} z_{c}^{u}+\sum_{h \in \mathcal{H}^{t}: i \in h} y_{h}^{t} \leq 1, \forall t \in \mathcal{T}, i \in \mathcal{V}^{t}$
- $w_{i r}^{t}+\sum_{\substack{c \in \mathcal{C}^{t}: \\ j \in c}} z_{c}^{t} \leq 1, \forall t \in \mathcal{T}, i \in \mathcal{V}^{t}, r \in \mathcal{R}_{i}, j \in \mathcal{I}_{r} \backslash\{i\}$
- $w_{i r}^{t} \leq \sum_{h \in \mathcal{H}^{t}: i \in h} y_{h}^{t}, \forall t \in \mathcal{T}, i \in \mathcal{V}^{t}, r \in \mathcal{R}_{i}$
- $\sum_{i \in h} \sum_{r \in \mathcal{R}_{i}} \mathrm{~s}_{i r} w_{i r}^{t} \geq \mathrm{C}^{\min } y_{h}^{t}, \forall t \in \mathcal{T}, h \in \mathcal{H}^{t}$
- $\sum_{i \in \mathcal{V}^{t}} \sum_{r \in \mathcal{R}_{i}} \mathrm{~s}_{i r} w_{i r}^{t} \geq \mathrm{C}^{\text {mintot }}, \forall t \in \mathcal{T}$
- $\sum_{h \in \mathcal{H}^{t}} \mathrm{~s}_{h} y_{h}^{t} \geq \mathrm{H}^{\text {mintot }}, \forall t \in \mathcal{T}$
- Polynomial number of constraints
- Exponential number of variables $\stackrel{\circ}{\square}$


## Branch-and-bound $\longrightarrow$

Solutions within $1 \%$ of the optimum in less than two hours
except
for the large instances, with solution gaps slightly above 7\% -

## Table: Approaches studied.

| Exact methods | Heuristics |
| :--- | :--- |
| Solve MILP models | Simulation |
| Branch-and-cut algorithm | Simulated annealing |
| Branch-and-bound algorithm | Tabu search |
| Multi-objective programming | Hybrid heuristics |
|  | Linear programming based heuristics |
|  | Dynamic programming-based heuristics |

## Obrigada!



Source: Os Espacialistas

