Optimal thinking in forest management with environmental concerns

Isabel Martins





1 Open problem

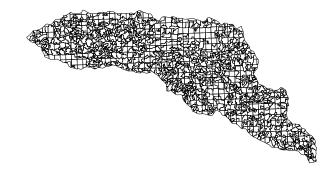
2 Methodologies

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Basic forestry problem



Source: Os Espacialistas

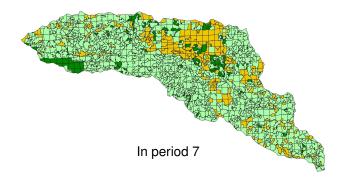


Forest area = 21147.8 ha # stands = 1363 # periods = 7

Maximize the profit from timber harvested over the planning horizon subject to:

- A regular production of timber in the planning horizon
- A minimum in the average age of the forest at the end of the planning horizon

• ...





Limiting clearcut size aims at reducing the impact on

- soil
- water quality
- wildlife
- scenic beauty

• ...

Mature patches



Forest patch = Edge + Core area

Core area - interior area of the patch where ecological functioning is not impacted by the effect of immediately surrounding conditions

Edge - buffer area separating core area from outside influences

Edge and core-dependent species



Edge-dependent species



Core-dependent species

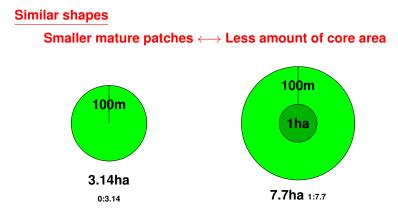
Core area

The core area of a forest patch is determined by the **area**, **shape and immediately surrounding conditions of the patch**

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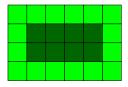
Area

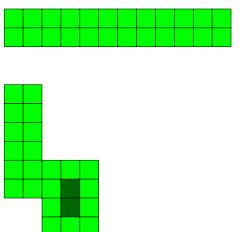


Shape

Similar areas

Elongated or complex shapes \longleftrightarrow Less amount of core area





Basic + clearcut constraints

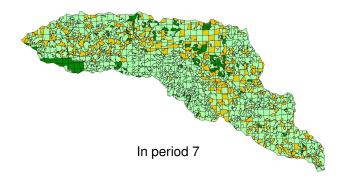


Source: Os Espacialistas

Basic + clearcut constraints

Maximize the profit from timber harvested over the planning horizon subject to:

- A regular production of timber in the planning horizon
- A minimum in the average age of the forest at the end of the planning horizon
- For each period, the area of every clearcut does not exceed the maximum allowed size



Basic + clearcut + habitat constraints

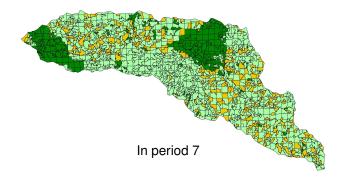


Source: Os Espacialistas

Basic + clearcut + habitat constraints

Maximize the profit from timber harvested over the planning horizon subject to:

- A regular production of timber in the planning horizon
- A minimum in the average age of the forest at the end of the planning horizon
- For each period, the area of every clearcut does not exceed the maximum allowed size
- Each habitat is a mature patch meeting a minimum core area
- In each period, the total core area inside habitats is greater than or equal to a minimum total core area



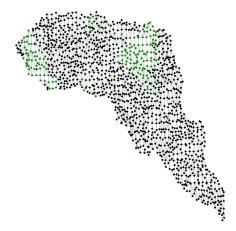


Open Problem 13 How can we include complex environmental considerations like fragmentation, corridors, balancing mature patches, etc. into URM and ARM formulations in a computationally feasible way?

It is well recognized now that adjacency constraints capture only a part of necessary environmental considerations. While maximum opening size limits are important, excessive fragmentation of forests is not particularly satisfactory. In order to allow wildlife to move between habitats, corridors of mature trees need to exist to join them. Similarly, issues of forest edge as well as a balance of mature forest are important for certain species. A few examples exist of attempting to address related issues using heuristic approaches. Thus, exact approaches are needed.







Connectivity



Source: Os Espacialistas

Models in MIP (A)

• $x_i^t = \begin{cases} 1 & \text{if stand } i \text{ is selected to be harvested in period } t \\ 0 & \text{otherwise} \end{cases}$

- $y_i^t = \begin{cases} 1 & \text{if stand } i \text{ is selected to be part of the core area of} \\ a habitat in period t \\ 0 & \text{otherwise} \end{cases}$

Models in MIP (A)

• $x_i^t = \begin{cases} 1 & \text{if stand } i \text{ is selected to be harvested in period } t \\ 0 & \text{otherwise} \end{cases}$

- $y_i^t = \begin{cases} 1 & \text{if stand } i \text{ is selected to be part of the core area of} \\ a habitat in period t \\ 0 & \text{otherwise} \end{cases}$
- $\sum_{i \in C} x_i^t \leq |C| 1; t \in T; C \in Cc^t$
- $\sum_{i\in\Pi^{t}(M)} y_{i}^{t} \geq y_{j}^{t}; t \in T; M \in \mathcal{M}h^{t}; j \in M$

•
$$\sum_{\substack{t' \leq t: \\ \mathcal{C}^{t'} \cap \{i\} \neq \emptyset}} x_i^{t'} \leq 1 - y_j^t; t \in T; j \in M^t; i \in \pi(j) \cup \{j\}$$

•
$$\sum_{i \in M^t} a_i y_i^t \ge COT_{\min}; t \in T$$

$$a_i = 1$$
 ha, $A_{max} = 2$ ha

1	2	3
4	5	6
7	8	9

Mature forest in period 1



Connected region, unfeasible as clearcut, minimal

1	2	3
4	5	6
7	8	9

1	2	3
4	5	6
7	8	9

1	2	3
4	5	6
7	8	9

1	2	3
4	5	6
7	8	9

1	2	3
4	5	6
7	8	9

 $x_1^1 + x_2^1 + x_3^1 \leq 2$

1	2	3
4	5	6
7	8	9

$$x_1^1 + x_2^1 + x_3^1 \le 2$$

 $\sum_{i \in C} x_i^t \le |C| - 1; \ t \in T; C \in Cc^t$

Core area

1	2	3
4	5	6
7	8	9

Mature forest in period 1



Connected region, unfeasible core area

1	2	3
4	5	6
7	8	9



1	2	3
4	5	6
7	8	9



1	2	3
4	5	6
7	8	9



1	2	3
4	5	6
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 $y_4^1 + y_8^1 \ge y_7^1$

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1	2	3
4	5	6
7	8	9

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1	2	3
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7	8	9

1	2	3
4	5	6
7	8	9

1	2	3
4	5	6
7	8	9

$$\begin{array}{l} y_4^1 + y_5^1 + y_9^1 \geq y_7^1 \\ y_4^1 + y_5^1 + y_9^1 \geq y_8^1 \end{array}$$

1	2	3
4	5	6
7	8	9

$$y_4^1 + y_5^1 + y_9^1 \ge y_7^1$$

 $y_4^1 + y_5^1 + y_9^1 \ge y_8^1$

$$\sum_{i\in\Pi^t(M)} y_i^t \ge y_j^t; t \in T; M \in \mathcal{M}h^t; j \in M$$

Habitat

Habitat

1	2	3
4	5	6
7	8	9

$$\sum_{\substack{t' \leq t: \\ \mathcal{C}^{t'} \cap \{i\} \neq \emptyset}} x_i^{t'} \leq 1 - y_j^t; t \in T; j \in M^t; i \in \pi(j) \cup \{j\}$$

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• Polynomial number of variables



• Exponential number of constraints

• Polynomial number of variables

Exponential number of constraints

 $\text{Branch-and-cut} \longrightarrow$

Solutions within 1% of the optimum in less than three hours







Models in MIP (B)

• $z_c^t = \begin{cases} 1 & \text{if region } c \in C^t \text{ is harvested in period } t \\ 0 & \text{otherwise} \end{cases}$

•
$$y_h^t = \begin{cases} 1 & \text{if region } h \in \mathcal{H}^t \text{ is habitat in period } t \\ 0 & \text{otherwise} \end{cases}$$

•
$$w_{ir}^t = \begin{cases} 1 & \text{if subregion } r \in \mathcal{R}_i \text{ is core habitat in period } t \\ 0 & \text{otherwise} \end{cases}$$



Region $c \in C^1$ that can be a clearcut in period 1 if ...

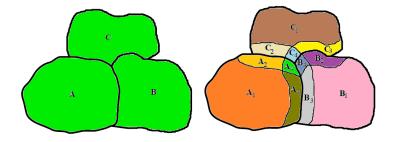
1	2	3
4	5	6
7	8	9

Habitats

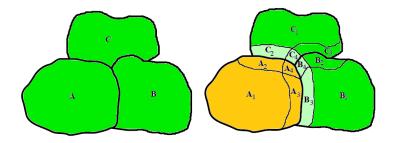
Region $h \in \mathcal{H}^1$ that can be a habitat in period 1 if ...

1	2	3
4	5	6
7	8	9

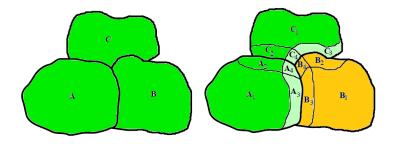
Core area - Subregions



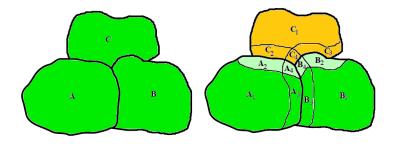




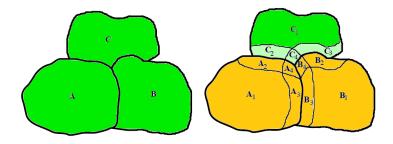












Constraints

•
$$\sum_{u=1}^{t} \sum_{c \in \mathcal{C}^{U}: i \in c} z_{c}^{u} + \sum_{h \in \mathcal{H}^{l}: i \in h} y_{h}^{l} \le 1, \forall t \in \mathcal{T}, i \in \mathcal{V}^{l}$$

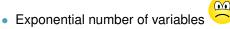
•
$$w_{ir}^t + \sum_{\substack{c \in \mathcal{C}^t: \\ j \in c}} z_c^t \le 1, \forall t \in \mathcal{T}, i \in \mathcal{V}^t, r \in \mathcal{R}_i, j \in \mathcal{I}_r \setminus \{i\}$$

•
$$w_{ir}^{t} \leq \sum_{h \in \mathcal{H}^{t}: i \in h} y_{h}^{t}, \forall t \in \mathcal{T}, i \in \mathcal{V}^{t}, r \in \mathcal{R}_{i}$$

- $\sum_{i \in h} \sum_{r \in \mathcal{R}_{i}} \mathbf{s}_{ir} \mathbf{w}_{ir}^{t} \ge \mathbf{C}^{\min} \mathbf{y}_{h}^{t}, \forall t \in \mathcal{T}, h \in \mathcal{H}^{t}$
- $\sum_{i \in \mathcal{V}^{t}} \sum_{r \in \mathcal{R}_{i}} s_{ir} w_{ir}^{t} \ge C^{\text{mintot}}, \forall t \in \mathcal{T}$
- $\sum_{h \in \mathcal{H}^{t}} \mathbf{s}_{h} \mathbf{y}_{h}^{t} \geq \mathbf{H}^{\text{mintot}}, \ \forall t \in \mathcal{T}$

Polynomial number of constraints





$Branch-and-bound \longrightarrow$

Solutions within 1% of the optimum in less than two hours



except

for the large instances, with solution gaps slightly above 7%



Table: Approaches studied.

Exact methods	Heuristics
Solve MILP models	Simulation
Branch-and-cut algorithm	Simulated annealing
Branch-and-bound algorithm	Tabu search
Multi-objective programming	Hybrid heuristics
	Linear programming based heuristics
	Dynamic programming-based heuristics

Obrigada!



Source: Os Espacialistas